## Mathematics I

Land Resources Management

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# Course Program – Linear Algebra

- 1. Vector spaces, vectors, and unit vectors (versors)
- 2. Types of matrices, operations on matrices, matrix rank
- 3. Determinants and their properties
- 4. Inverse matrix
- 5. Systems of linear equations Cramer's rule
- 6. Methods of solving systems of equations, Gaussian elimination method
- 7. Eigenvalues and eigenvectors
- 8. Generalized inverse matrix (optional / to be confirmed)

# Rectangular and Square Matrices Definition of a Matrix

#### **Definition:**

A matrix is any array of numbers arranged in rows and columns. If a matrix has m rows and n columns, we say that it has dimension  $m \times n$  and we write:

$$\mathbf{A} = [a_{ij}], \quad i = 1, 2, \dots, m, \quad j = 1, 2, \dots, n$$

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \dots & a_{mn} \end{bmatrix}$$

## Rectangular and Square Matrices Column and Row Vectors of a Matrix

#### **Definition:**

A *column vector* of a matrix **A** of dimension  $m \times n$  is any submatrix of dimension  $m \times 1$ . Every matrix can be divided into n column vectors.

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \dots & a_{mn} \end{bmatrix}$$

#### **Definition:**

A row vector of a matrix **A** of dimension  $m \times n$  is any submatrix of dimension  $1 \times n$ . Every matrix can be divided into m row vectors.

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \dots & a_{mn} \end{bmatrix}$$

# Rectangular and Square Matrices Zero Matrix and Square Matrix

#### **Definition:**

A zero matrix of dimension  $m \times n$  is a matrix consisting entirely of zeros.

That is, if  $A=0_{m\times n}$ , then  $a_{ij}=0$  for all i and j.

$$\mathbf{A} = \mathbf{0}_{\text{mxn}} = \begin{bmatrix} 0 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 \end{bmatrix}$$

#### **Definition:**

If the number of rows equals the number of columns (m=n), then such an array of numbers is called a square matrix.

The elements  $a_{11}, a_{22}, ..., a_{nn}$  form the diagonal of the matrix.

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix}$$

# Rectangular and Square Matrices Upper Triangular and Lower Triangular Matrices

#### **Definition:**

A square matrix such that  $a_{ij}$ =0 for i>j is called an upper triangular matrix.

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ 0 & a_{22} & \dots & a_{2n} \\ & & \ddots & \dots & \ddots \\ 0 & 0 & \dots & a_{nn} \end{bmatrix}$$

#### **Definition:**

A square matrix such that  $a_{ij}$ =0 for i<j is called *a lower triangular* matrix.

$$\begin{bmatrix} a_{11} & 0 & \dots & 0 \\ a_{21} & a_{22} & \dots & 0 \\ & & \ddots & \dots & \ddots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix}$$

# Rectangular and Square Matrices Diagonal and Identity Matrices

#### **Definition:**

A square matrix such that  $a_{ij}=0$  for  $i\neq j$  is called a diagonal matrix.

$$\begin{bmatrix} a_{11} & 0 & \dots & 0 \\ 0 & a_{22} & \dots & 0 \\ & & \ddots & \dots & \ddots \\ 0 & 0 & \dots & a_{nn} \end{bmatrix}$$

#### **Definition:**

Every diagonal matrix in which  $a_{ii}$ =1 is called an identity matrix and is denoted by  $\mathbf{I}$  or  $\mathbf{I}_{n}$ 

$$\mathbf{I} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ & & & \ddots & \ddots \\ 0 & 0 & \dots & 1 \end{bmatrix}$$

### **Matrix Equality**

Two matrices **A** and **B** of the same dimension  $m \times n$  are said to be equal if and only if all corresponding elements are equal, that is,

$$\mathbf{A} = \mathbf{B} \quad \Leftrightarrow \quad a_{ij} = b_{ij} \quad ext{for all } i,j.$$

#### **Addition of Matrices**

Let  $\mathbf{A} = [a_{ij}]$  and  $\mathbf{B} = [b_{ij}]$  be matrices of dimension  $m \times n$ . The sum of matrices  $\mathbf{A}$  and  $\mathbf{B}$  is the matrix  $\mathbf{C} = [c_{ij}]$ , denoted  $\mathbf{C} = \mathbf{A} + \mathbf{B}$ , whose elements are defined by:

$$c_{ij} = a_{ij} + b_{ij}, \quad i = 1, 2, \dots, m, \ j = 1, 2, \dots, n.$$

## Addition of Matrices

$$\mathbf{A} + \mathbf{B} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} + \begin{bmatrix} b_{11} & b_{12} & \dots & b_{1n} \\ b_{21} & b_{22} & \dots & b_{2n} \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ b_{m1} & b_{m2} & \dots & b_{mn} \end{bmatrix} = \begin{bmatrix} a_{11} + b_{11} & a_{12} + b_{12} & \dots & a_{1n} + b_{1n} \\ a_{21} + b_{21} & a_{22} + b_{22} & \dots & a_{2n} + b_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{m1} + b_{m1} & a_{m2} + b_{m2} & \dots & a_{mn} + b_{mn} \end{bmatrix}$$

$$\mathbf{A} + \mathbf{B} = \begin{bmatrix} 1 & 0 & -2 & 4 \\ 5 & 2 & 1 & 0 \\ -3 & 4 & 1 & 2 \end{bmatrix} + \begin{bmatrix} 2 & -1 & 3 & 1 \\ -2 & 1 & 0 & 2 \\ 0 & 2 & 5 & 3 \end{bmatrix} = \begin{bmatrix} 1+2 & 0+(-1) & -2+3 & 4+1 \\ 5+(-2) & 2+1 & 1+0 & 0+2 \\ -3+0 & 4+2 & 1+5 & 2+3 \end{bmatrix} = \begin{bmatrix} 3 & 3 & 1 & 2 \\ -3 & 6 & 6 & 5 \end{bmatrix}$$

## Subtraction of Matrices

#### **Subtraction of Matrices**

Let  $\mathbf{A} = [a_{ij}]$  and  $\mathbf{B} = [b_{ij}]$  be matrices of dimension  $m \times n$ . The *difference* of matrices  $\mathbf{A}$  and  $\mathbf{B}$  is the matrix  $\mathbf{C} = [c_{ij}]$ , denoted  $\mathbf{C} = \mathbf{A} - \mathbf{B}$ , whose elements are defined by:

$$c_{ij} = a_{ij} - b_{ij}, \quad i = 1, 2, \dots, m, \ j = 1, 2, \dots, n.$$

### Subtraction of Matrices

$$\mathbf{A} - \mathbf{B} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \dots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} - \begin{bmatrix} b_{11} & b_{12} & \dots & b_{1n} \\ b_{21} & b_{22} & \dots & b_{2n} \\ \vdots & \vdots & \dots & \vdots \\ b_{m1} & b_{m2} & \dots & b_{mn} \end{bmatrix} = \begin{bmatrix} a_{11} - b_{11} & a_{12} - b_{12} & \dots & a_{1n} - b_{1n} \\ a_{21} - b_{21} & a_{22} - b_{22} & \dots & a_{2n} - b_{2n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{m1} - b_{m1} & a_{m2} - b_{m2} & \dots & a_{mn} - b_{mn} \end{bmatrix}$$

$$\mathbf{A} - \mathbf{B} = \begin{bmatrix} 1 & 0 & -2 & 4 \\ 5 & 2 & 1 & 0 \\ -3 & 4 & 1 & 2 \end{bmatrix} - \begin{bmatrix} 2 & -1 & 3 & 1 \\ -2 & 1 & 0 & 2 \\ 0 & 2 & 5 & 3 \end{bmatrix} = \begin{bmatrix} 1-2 & 0-(-1) & -2-3 & 4-1 \\ 5-(-2) & 2-1 & 1-0 & 0-2 \\ -3-0 & 4-2 & 1-5 & 2-3 \end{bmatrix} = \begin{bmatrix} -1 & 1 & -5 & 3 \\ 7 & 1 & 1 & -2 \\ -3 & 2 & -4 & -1 \end{bmatrix}$$

### Multiplication of a Matrix by a Scalar

### Multiplication of a Matrix by a Scalar

Let  $\mathbf{A} = [a_{ij}]$  be a matrix of dimension  $m \times n$ , and let c be a real number (a scalar). The product of the matrix  $\mathbf{A}$  by the scalar c is the matrix  $\mathbf{B} = [b_{ij}]$ , (denoted  $\mathbf{B} = c\mathbf{A}$ ), whose elements are defined by:

$$b_{ij} = c \cdot a_{ij}, \quad i = 1, 2, \dots, m, \ j = 1, 2, \dots, n.$$

$$c\mathbf{A} = \begin{bmatrix} 1 & 0 & -2 & 4 \\ 5 & 2 & 1 & 0 \\ -3 & 4 & 1 & 2 \end{bmatrix} = \begin{bmatrix} 3 & 0 & -6 & 12 \\ 15 & 6 & 3 & 0 \\ -9 & 12 & 3 & 6 \end{bmatrix}$$

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## Properties of Matrix Addition and Scalar Multiplication

Let  $\mathbf{A}, \mathbf{B}, \mathbf{C}$  be matrices of the same dimension m imes n, and let  $c, d \in \mathbb{R}$  be real numbers.

The following properties hold:

1. Commutativity:

$$A + B = B + A$$

2. Associativity:

$$(A + B) + C = A + (B + C)$$

3. Additive Identity:

$$A + 0 = A$$

4. Additive Inverse:

$$A + (-A) = 0$$

5. Distributivity (Matrix Addition):

$$c(A + B) = cA + cB$$

6. Distributivity (Scalar Addition):

$$(c + d)A = cA + dA$$

7. Associativity (Scalars):

$$(cd)A = c(dA)$$

8. Multiplicative Identity:

$$1 \cdot A = A$$

# Rectangular and Square Matrices Matrix Multiplication

Matrix Multiplication  $A \cdot B = AB = C$ :

The product A·B is defined only if the number of columns in A equals the number of rows in B.

Let  $A=[a_{ij}]$  be a matrix of dimension  $m \times n$  and

 $\mathbf{B} = [b_{ik}]$  a matrix of dimension  $n \times p$ .

The *product* of matrices **A** and **B** is a matrix  $C=[c_{ik}]$  of dimension  $m \times p$ , defined as:

$$\mathbf{C} = \mathbf{AB}, \qquad c_{ik} = a_{i1}b_{1k} + a_{i2}b_{2k} + ... + a_{in}b_{nk} = \sum_{j=1}^{n} a_{ij}b_{jk}$$

#### Remarks:

- Matrix multiplication is not commutative, i.e. in general  $\mathbf{AB} \neq \mathbf{BA}$ .
- However, for some special matrices (e.g. diagonal or scalar multiples of the identity), commutativity may hold.

## Rectangular and Square Matrices Matrix Multiplication — Example

$$\mathbf{AB} = \begin{bmatrix} 2 \\ 0 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \cdot 3 + 2 \cdot 1 \\ 0 \cdot 3 + (-1) \cdot 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \cdot 1 + 2 \cdot 2 \\ 0 \cdot 3 + (-1) \cdot 2 \end{bmatrix} = \begin{bmatrix} 5 \\ 5 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 5 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

# Rectangular and Square Matrices Matrix Transposition

### **Matrix Transposition**

The *transpose* of a matrix A, denoted  $-A^{T}$  is the matrix obtained by interchanging the rows and columns of A.

$$(\mathbf{A}^T)_{ij} = a_{ji}, \quad \text{for all } i, j.$$

**Example:** 

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & -2 & 4 \\ 5 & 2 & 1 & 0 \\ -3 & 4 & 1 & 2 \end{bmatrix} \qquad \mathbf{A}^{\mathrm{T}} = \begin{bmatrix} 1 & 5 & -3 \\ 0 & 2 & 4 \\ -2 & 1 & 1 \\ 4 & 0 & 2 \end{bmatrix}$$

# Rectangular and Square Matrices Properties of Matrix Operations

$$\mathbf{A}(\mathbf{B} + \mathbf{C}) = \mathbf{A}\mathbf{B} + \mathbf{A}\mathbf{C} \qquad (\mathbf{A}\mathbf{B})\mathbf{C} = \mathbf{A}(\mathbf{B}\mathbf{C})$$
$$(\mathbf{A} + \mathbf{B})\mathbf{C} = \mathbf{A}\mathbf{C} + \mathbf{B}\mathbf{C} \qquad \mathbf{A}\mathbf{I}_{n} = \mathbf{I}_{m}\mathbf{A} = \mathbf{A}$$

$$\mathbf{A}(\mathbf{c}\mathbf{B}) = (\mathbf{c}\mathbf{A})\mathbf{B} = \mathbf{c}\mathbf{A}\mathbf{B}$$
  $\mathbf{A}\mathbf{0}_{\text{nxp}} = \mathbf{0}_{\text{mxp}}$ 

$$(\mathbf{A}^T)^T = \mathbf{A},$$
 $(\mathbf{A} + \mathbf{B})^T = \mathbf{A}^T + \mathbf{B}^T,$ 
 $(c\mathbf{A})^T = c\mathbf{A}^T,$ 
 $(\mathbf{A}\mathbf{B})^T = \mathbf{B}^T\mathbf{A}^T.$ 

# Square Matrices Trace of a Matrix

#### **Trace of a Matrix**

The trace of a square matrix A, denoted tr(A), is the sum of the elements on its main diagonal:

$$\mathrm{tr}(\mathbf{A}) = \sum_{i=1}^n a_{ii}.$$

$$tr(\mathbf{A}) = tr(\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1m} \\ a_{21} & a_{22} & \dots & a_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mm} \end{bmatrix}) = \sum_{i=1}^{m} a_{ii} = a_{11} + a_{22} + \dots + a_{mm}$$

$$tr(\mathbf{A}) = tr(\begin{bmatrix} 1 & -2 & 1 \\ 3 & 2 & 3 \\ -1 & 4 & 3 \end{bmatrix}) = 1 + 2 + 3 = 6$$

# Square Matrices Trace of a Matrix

$$tr(c\mathbf{A}) = c \cdot tr(\mathbf{A})$$
  $tr(\mathbf{A} + \mathbf{B}) = tr(\mathbf{A}) + tr(\mathbf{B})$   $tr(\mathbf{A}) = tr(\mathbf{A}^T)$ 

$$tr(4\mathbf{A}) = tr(4\begin{bmatrix} 1 & -2 & 1 \\ 3 & 2 & 3 \\ -1 & 4 & 3 \end{bmatrix}) = tr(\begin{bmatrix} 4 & -8 & 4 \\ 12 & 8 & 12 \\ -4 & 16 & 12 \end{bmatrix}) = 4 \cdot 6 = 24$$
 
$$tr(\mathbf{A}) = tr(\begin{bmatrix} 1 & -2 & 1 \\ 3 & 2 & 3 \\ -1 & 4 & 3 \end{bmatrix}) = 6 = tr(\mathbf{A}^{\mathrm{T}}) = tr(\begin{bmatrix} 1 & 3 & -1 \\ -2 & 2 & 4 \\ 1 & 3 & 3 \end{bmatrix})$$

$$\operatorname{tr}(\mathbf{A} + \mathbf{B}) = \operatorname{tr}(\mathbf{A}) + \operatorname{tr}(\mathbf{B}) = \operatorname{tr}\begin{pmatrix} 1 & -2 & 1 \\ 3 & 2 & 3 \\ -1 & 4 & 3 \end{pmatrix} + \operatorname{tr}\begin{pmatrix} 1 & -1 & 1 \\ 1 & 1 & 1 \\ -1 & 1 & 1 \end{pmatrix} = 6 + 3 = 9$$

## Linearly Independent Vectors

#### **Definition:**

A family of vectors  $\mathbf{a}_1$ ,  $\mathbf{a}_2$ , ...,  $\mathbf{a}_k$  is said to be *linearly independent* if the only solution of the equation

$$c_1\mathbf{a_1} + c_2\mathbf{a_2} + \dots + c_k\mathbf{a_k} = \mathbf{0}$$

is

$$c_1=c_2=\cdots=c_k=0.$$

#### Note:

If the above equation also has a non-zero solution, then the vectors  $\mathbf{a}_1, \mathbf{a}_2, ..., \mathbf{a}_k$  are *linearly dependent*.

# Rectangular and Square Matrices Rank of a Matrix and Non-Singular Matrices

#### **Definition:**

The rank of a matrix A is the maximum number of linearly independent vectors(rows or columns) in the matrix. It is denoted by rank A or  $r_a = rz$  A

#### **Definition:**

The rank of a matrix is equal to the highest order of any non-zero determinant of its square submatrices (i.e. the highest order of its non-singular minor). (see L. 3 and 4).

In practice, the rank of a matrix **A** is found by transforming it into its *echelon form* using *elementary operations*.

## Rectangular and Square Matrices Echelon (Canonical) Form of a Matrix

The *echelon form* (or row-echelon form) of a matrix A is obtained by performing a sequence of elementary transformations on the rows (and possibly columns) of A.

#### In echelon form:

- all zero rows, if any, appear at the bottom of the matrix,
- the leading non-zero entry in each non-zero row lies to the right of the leading entry in the row above.

$$\mathbf{A} = \begin{bmatrix} \mathbf{I}_{k} & \mathbf{R} \\ \mathbf{0} & \mathbf{0} \end{bmatrix} \Rightarrow rz\mathbf{A} = k$$

$$\mathbf{A} = \begin{bmatrix} 5 & 2 & 1 & -2 \\ -1 & 3 & 0 & -3 \\ 0 & 2 & -1 & -2 \\ 1 & -3 & 0 & 3 \\ 10 & 4 & 2 & -4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} \mathbf{I}_3 & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix} \Rightarrow rz\mathbf{A} = 3$$

## Elementary Transformations Used to Determine the Rank

1. Add to one row another row multiplied by a non-zero scalar:

$$W_i o W_i + cW_j$$

2. Add to one column another column multiplied by a non-zero scalar:

$$K_i o K_i + cK_j$$

**3.** Multiply a row by a non-zero scalar:

$$W_i 
ightarrow cW_i$$

**4.** Multiply a column by a non-zero scalar:

$$K_i o c K_i$$

**5.** Interchange two rows:

$$W_i \leftrightarrow W_j$$

**6.** Interchange two columns:

$$K_i \leftrightarrow K_j$$

# Rectangular and Square Matrices Rank of a Matrix — Example

Example:

$$rz\mathbf{A} = rz \begin{bmatrix} 5 & 2 & 1 \\ -1 & 3 & 0 \\ 0 & 2 & -1 \end{bmatrix} = ?$$

$$\Rightarrow rz\mathbf{A} = 3$$

### **Linearly Independent Vectors**

In  $\mathbb{R}^3$ 

$$rz\mathbf{A} = rz\begin{bmatrix} 5 & 2 & 1 \\ -1 & 3 & 0 \\ 0 & 2 & -1 \end{bmatrix} = 3$$

$$\mathbf{a_1} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}, \mathbf{a_2} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}, \mathbf{a_3}$$

$$c_1\mathbf{a_1} + c_2\mathbf{a_2} + c_3\mathbf{a_3} = \mathbf{0}$$

Since rank A = 3, both the column vectors and the row vectors of matrix **A** are linearly independent.

$$\operatorname{rank}(\mathbf{A}) = 3 \;\; \Rightarrow \;\; c_1 = c_2 = c_3 = 0$$

$$\mathbf{a_1} = \begin{bmatrix} 5 \\ -1 \\ 0 \end{bmatrix}, \mathbf{a_2} = \begin{bmatrix} 2 \\ 3 \\ 2 \end{bmatrix}, \mathbf{a_3} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$$

$$c_1 \mathbf{a}_1 + c_2 \mathbf{a}_2 + c_3 \mathbf{a}_3 = 0$$

$$c_{1} \begin{bmatrix} 5 \\ -1 \\ 0 \end{bmatrix} + c_{2} \begin{bmatrix} 2 \\ 3 \\ 2 \end{bmatrix} + c_{3} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} = \mathbf{0}$$

## Rectangular and Square Matrices Echelon (Canonical) Form of a Matrix

#### **Example:**

$$rz\mathbf{A} := rz \begin{bmatrix} 1 & 2 & 3 & -3 \\ -1 & -3 & 5 & 3 \\ 3 & 6 & 9 & -9 \\ 1 & 1 & 11 & -3 \end{bmatrix} \overset{W_2 \to W_2 + W_1}{=} \qquad rz \begin{bmatrix} 1 & 2 & 3 & -3 \\ 0 & -1 & 8 & 0 \\ 3 & 6 & 9 & -9 \\ 1 & 1 & 11 & -3 \end{bmatrix} \overset{W_3 \to W_3 - 3W_1}{=}$$

$$= rz \begin{bmatrix} 1 & 2 & 3 & -3 \\ 0 & -1 & 8 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 11 & -3 \end{bmatrix} \xrightarrow{W_4 \to W_4 - W_1} rz \begin{bmatrix} 1 & 2 & 3 & -3 \\ 0 & -1 & 8 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & -1 & 8 & 0 \end{bmatrix} \xrightarrow{W_4 \to W_4 - W_2} =$$

$$= rz \begin{bmatrix} 1 & 2 & 3 & -3 \\ 0 & -1 & 8 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}^{K_2 \to K_2 - 2K_1} = rz \begin{bmatrix} 1 & 0 & 3 & -3 \\ 0 & 1 & 8 & 0 \\ \hline 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = rz \begin{bmatrix} \mathbf{I} & \mathbf{R} \\ \mathbf{0} & \mathbf{0} \end{bmatrix} \Rightarrow rz\mathbf{A} = 2$$

## **Square Matrices**

### **Symmetric Matrix:**

A *symmetric* matrix is a square matrix A such that  $\mathbf{A} = \mathbf{A}^{T}$ . That is, the matrix remains unchanged when transposed.

$$\mathbf{A} = \begin{bmatrix} a & d & e \\ d & b & f \\ e & f & c \end{bmatrix} = \mathbf{A}^{T} \underbrace{\mathbf{A} + \mathbf{A}^{T} = ?}$$

### **Skew-Symmetric Matrix:**

A *skew-symmetric* matrix (also called antisymmetric) is a square matrix A satisfying the relation  $A=-A^{T}$ .

$$\mathbf{A} = \begin{bmatrix} 0 & d & e \\ -d & 0 & f \\ -e & -f & 0 \end{bmatrix} = -\mathbf{A}^{\mathrm{T}} \qquad \mathbf{A} - \mathbf{A}^{\mathrm{T}} = ?$$

#### **Remark:**

For every skew-symmetric matrix, all elements on the main diagonal are equal to zero.

## **Square Matrices**

#### **Hilbert Matrix:**

A Hilbert matrix is a symmetric square matrix A=[1/(i+j)], where i, j = 1, 2, ..., m

$$\mathbf{A} = \begin{bmatrix} \frac{1}{1+1} & \frac{1}{1+2} & \frac{1}{1+3} \\ \frac{1}{2+1} & \frac{1}{2+2} & \frac{1}{2+3} \\ \frac{1}{3+1} & \frac{1}{3+2} & \frac{1}{3+3} \end{bmatrix} = \mathbf{A}^{\mathrm{T}}$$

### **Commutative Matrices**

Two square matrices **A** and **B** are said to be commutative if their product does not depend on the order of multiplication, i.e.

$$AB = BA$$
.